

# Error and Noise



## Error Measures

An error measure quantifies the performance of an  $h \in \mathcal{H}$ , that is, its agreement with the target function  $f$ .

$$\text{Error} = E(h, f)$$

The target function is unknown and we only have samples from it (our data set,  $\mathcal{D}$ ), so we use a pointwise approximation.

Classification error is

$$e(h(\vec{x}), f(\vec{x})) = \llbracket h(\vec{x}) \neq f(\vec{x}) \rrbracket$$

for some  $\vec{x}$ , where  $\llbracket \cdot \rrbracket$  evaluates to 1 if argument is true, and to 0 if it is false.

## Error Rate and Accuracy Rate

Given the previous pointwise definition of error, error rate within a data set  $\mathcal{D}$  can be defined as

$$E(h) = \frac{1}{N} \sum_{n=1}^N \llbracket h(\vec{x}) \neq f(\vec{x}) \rrbracket$$

In other words, it's the proportion of points in  $\mathcal{D}$  that are misclassified by  $h$ . If you turn the inequality above into an equality, you have *accuracy*, that is, accuracy =  $1 - E$ . Some prefer to think in terms of accuracy.

## Training Error and Test Error

The  $E$  we just defined is the error of our  $h$  in  $\mathcal{D}$ , a set of samples from  $\mathcal{X}$ . The book refers to this quantity as *in-sample* error, or  $E_{in}$ .

- ▶ With our data set  $\mathcal{D}$  we can only deal with  $E_{in}$ .
- ▶ What we really care about is  $E_{out}$  – how will our classifier perform on any possible unseen  $\vec{x}$  from  $\mathcal{X}$ .

So in practice we separate our data set  $\mathcal{D}$  into a training set and a test set.

- ▶  $E_{train}$  is the error rate on our training set.
- ▶  $E_{test}$  is the error rate on our test set.

We use  $E_{test}$  as an estimate of  $E_{out}$ . For this estimate to be meaningful we must observe the most critical rule in practical machine learning

*You must not use any data from the test set during training.*

## Cost

$E$  can be thought of as the *cost* of using  $h$  instead of  $f$  (if you knew  $f$  you'd just use  $f$ ). But the error measure we just defined might not be enough. Consider the case of identification by fingerprint<sup>1</sup>:


$$\rightarrow f \rightarrow \begin{cases} +1 \text{you} \\ -1 \text{not you} \end{cases}$$

Is the cost of correctly identifying a person the same for all applications?

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<sup>1</sup>Fingerprint image by Cyrillic at the English language Wikipedia, CC BY-SA 3.0, <https://commons.wikimedia.org/w/index.php?curid=3335963>

## Kinds of Error

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		f	
		+1	-1
h	+1	no error	false positive
	-1	negative	no error

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Consider the following two kinds of applications:

- ▶ Customer identification for a supermarket discount program
- ▶ Identification for authorization to enter CIA building

Is the cost for each kind of error the same?

## Cost Matrix

We can capture the relative cost of each kind of error in a cost matrix.

		$f$	
		$+1$	$-1$
$h$	$+1$	0	1
	$-1$	10	0

Supermarket

		$f$	
		$+1$	$-1$
$h$	$+1$	0	1000
	$-1$	1	0

CIA

- ▶ Accidentally letting someone into the CIA building is 1000 times worse than accidentally rejecting someone
- ▶ A learning algorithm using a cost-weighted error function will minimize the right kind of error

## Additional Error Metrics

Our earlier error function didn't distinguish between different kinds of errors – only misclassifications.

Let

- ▶  $TP$  be the number of true positive predictions,
- ▶  $TN$  be the number of true negative predictions,
- ▶  $FP$  be the number of false positive predictions, and
- ▶  $FN$  be the number of false negative predictions.

Then ...

## Precision, Recall, F-measure

- ▶  $Precision = \frac{TP}{TP+FP}$ 
  - ▶ If high, a positive prediction is likely correct (good for CIA entry)
  - ▶ Also called “hit rate”
- ▶  $Recall = \frac{TP}{TP+FN}$ 
  - ▶ If high, missed few positives but maybe had some false positives
  - ▶ Also called “false alarm rate”
  - ▶ Good for cancer diagnosis - better to scare someone than to miss an actual cancer
- ▶  $F1 - score = 2 \cdot \frac{Precision \cdot Recall}{Precision + Recall}$ 
  - ▶ If high, good precision *and* recall summarized in a single metric

## Confusion Matrix

We can calculate the error metrics from a *confusion matrix*. A confusion matrix lists the counts of the different kinds of errors. We've switched the positions of the true function,  $f$ , and our learned hypothesis,  $h$ , to match the output of most machine learning libraries.

Let's say we run a simple linear discriminant analysis on the [Wisconsin Breast Cancer Diagnostic data set](#) and get the following confusion matrix:

		h	
		+1	-1
truth	+1	48	7
	-1	0	88

## Evaluating a Model using Precision, Recall, and F-measure

		h	
		+1	-1
truth	+1	48	7
	-1	0	88

Using these values,

- ▶  $Precision = \frac{TP}{TP+FP} = \frac{48}{48+0} = 1.0$
- ▶  $Recall = \frac{TP}{TP+FN} = \frac{48}{48+7} = 0.87$
- ▶  $F1 - score = 2 \cdot \frac{Precision \cdot Recall}{Precision + Recall} = 2 \cdot \frac{1.0 \cdot 0.87}{1.0 + 0.87} = 0.93$

Forget, for a moment, that this model was evaluated on a breast cancer detection data set.

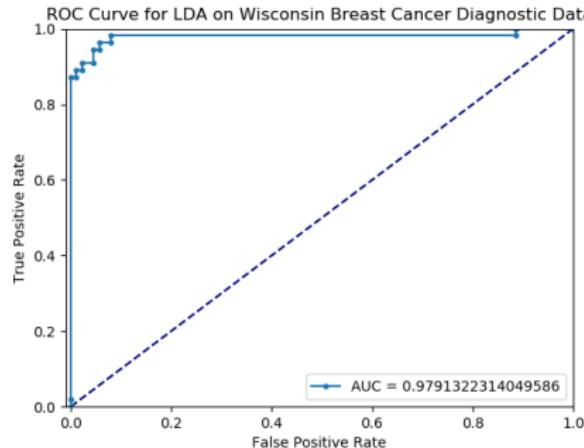
- ▶ For what kinds of applications would this be a good result?
- ▶ For what kinds of applications would this be a bad result?

BTW, the simple accuracy rate for this classifier would be

$$\frac{48+88}{48+88+7} = 0.95$$

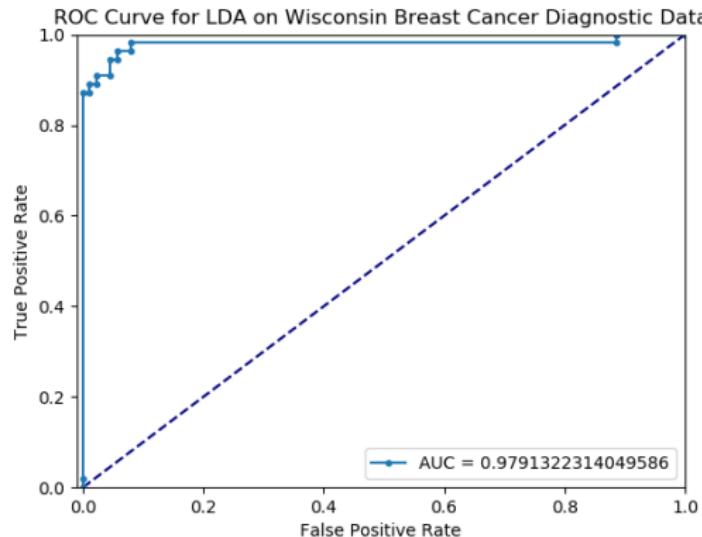
# ROC Curves

A *receiver operating characteristics curve*<sup>2</sup>, or *ROC* curve, plots the tp-rate versus the fp-rate to show the tradeoffs of a particular model on a particular data set. Here's a ROC curve for a linear discriminant analysis model on the breast cancer data:



How do we interpret a ROC curve? ...

# Interpreting ROC Curves



- ▶ A better ROC curve will “hug” the upper-left corner
- ▶ Area under the curve, or AUC, is a good single-number measure of overall performance.

Calculating the previous metrics is straightforward, but plotting ROC curve requires internal data used by a model. Let's see this in **code** ...

## Closing Thoughts

- ▶ Error (aka cost, aka loss) is the difference between the true target function and our hypothesis.
- ▶ We estimate the error with pointwise evaluations and a learning algorithm may optimize this directly.
- ▶ We train a model using a training set and evaluate it (estimate true error) by calculating error on a test set.
- ▶ There are two kinds of errors: false positives and false negatives.
  - ▶ We can characterize the cost of the different kinds of errors for a particular application.
- ▶ Simple error or accuracy rate is a poor metric.
- ▶ We can count the true positives, false positives, true negatives and false negatives in a classifier's predictions on the test set.
  - ▶ Using these counts we can calculate more fine-grained metrics for evaluating a classifier.
  - ▶ A ROC curve can give us a good general view of a classifier's general performance and tradeoffs.

and finally . . .

## The Golden Rule

We must *never* use test data for training.

- ▶ Ideally we'd have a test set unavailable to us (like in competitions).
- ▶ In practice we split a data set into training and test sets during model development

In case you missed it,

***WE MUST NEVER USE TEST DATA FOR TRAINING.***